Binary Trees

Lecture 12

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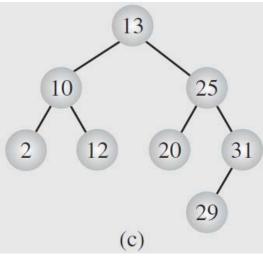
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Adapted partially from Data Structures and Algorithms in Java, M.T. Goodrich, R.Tamassia and M. H. Goldwasser, Sixth Edition, Wiley; Data Structures and Algorithms in C++, Adam Drozdek, 4th Edition, Cengage Learning



Tree Traversal

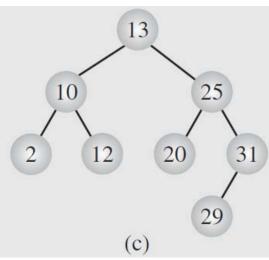
- Tree traversal: the process of visiting each node in a tree data structure exactly one time
 - visiting nodes, but no visiting order specified
 - numerous possible tree traversals
 - e.g., in a tree of *n* nodes, there are *n*! traversals
 - most of them are chaotic and no regularity
 - two possible traversals
 - **2**, 10, 12, 20, 13, 25, 29, 31
 - lists even numbers and then odd numbers in ascending order
 - **29, 31, 20, 12, 2, 25, 10, 13**
 - lists all nodes from level to level right to left, starting from the lowest level up to the root





Tree Traversal

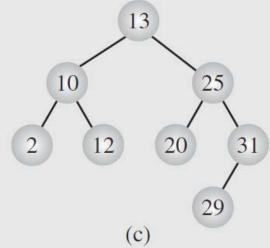
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 - another possible traversal
 - **13, 31, 12, 2, 10, 29, 20, 25**
 - no regularity;
 - random jumping from node to node



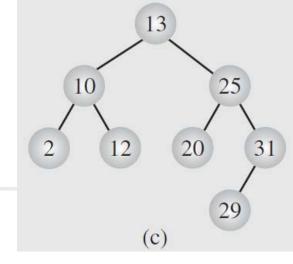


Tree Traversal

- Tree traversal: the process of visiting each node in a tree data structure exactly one time
 - visiting nodes, but no visiting order specified
 - numerous possible tree traversals
 - e.g., in a tree of *n* nodes, there are *n*! traversals
 - most of them are chaotic and no regularity
- Two useful traversals
 - depth-first traversals
 - breadth-first traversals







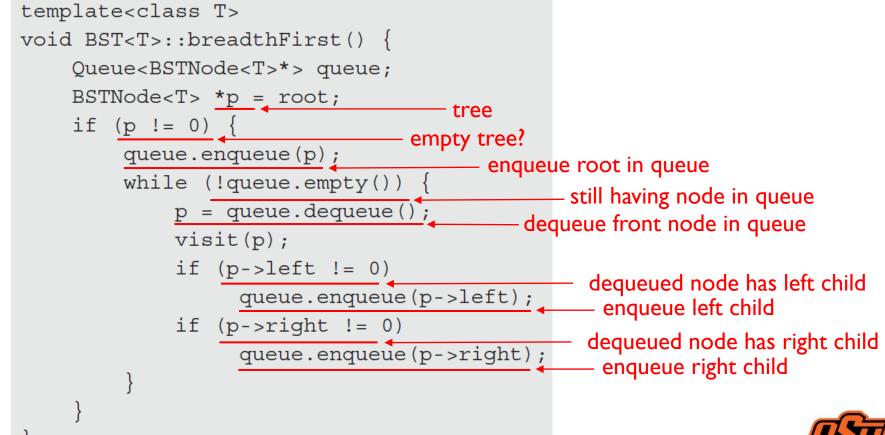
Breadth-First Traversal

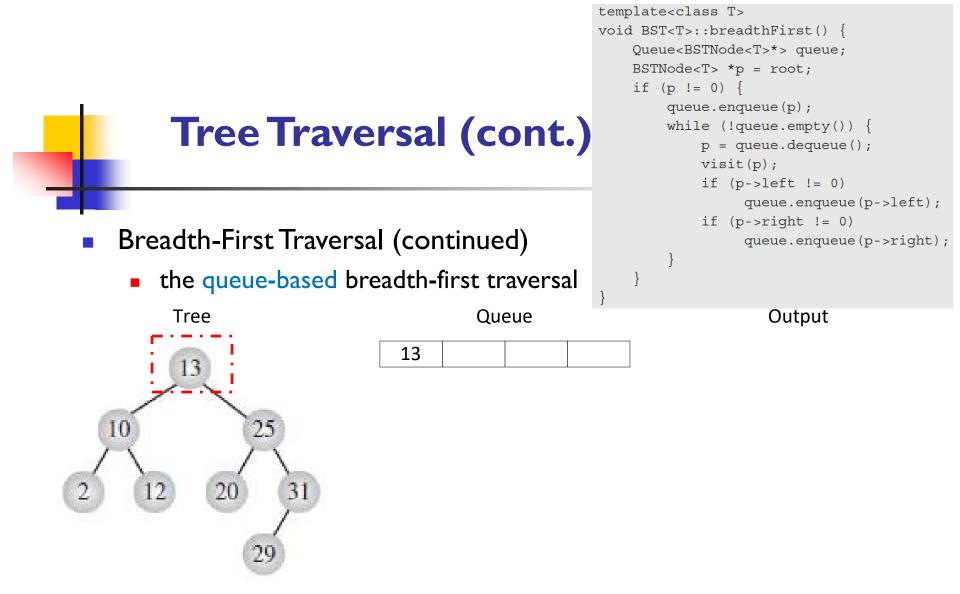
- visit each node in the tree
- start from lowest (or highest) level and move down (or up) level by level
 - on each level, visit node from left to right (or from right to left)
- one of four possible traversals
 - e.g., 13, 10, 25, 2, 12, 20, 31, 29 (top-down, left-to-right)
- Implement using a queue; consider a top-down, left-to-right breadth-first traversal
 - start by placing the root node in the queue
 - then remove the node at the front of the queue
 - after visiting it, place its children (if any) at the end of the queue
 - repeat until the queue is empty all nodes on level n must be visited

before visiting nodes on level *n*+1

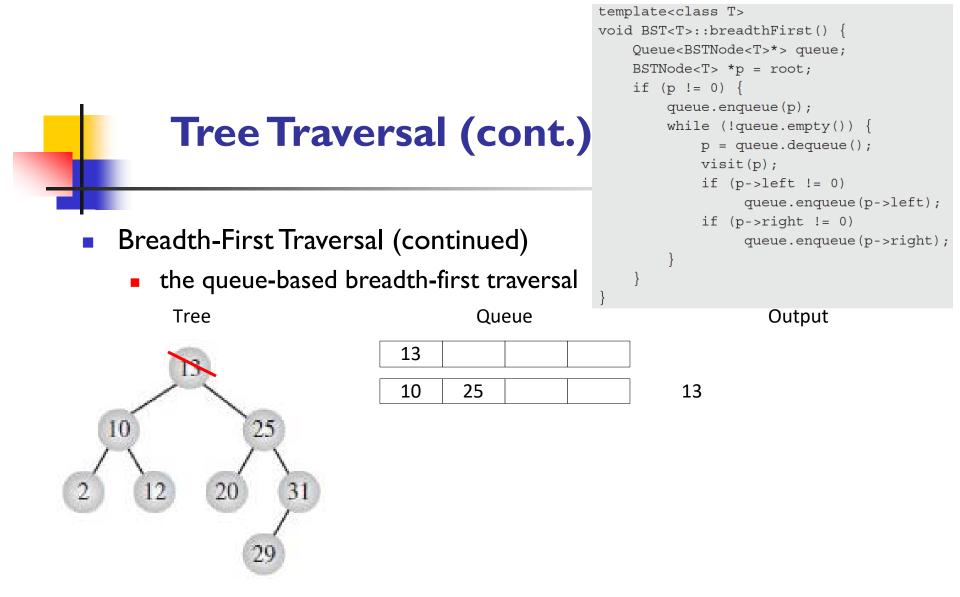


Breadth-First Traversal (continued)

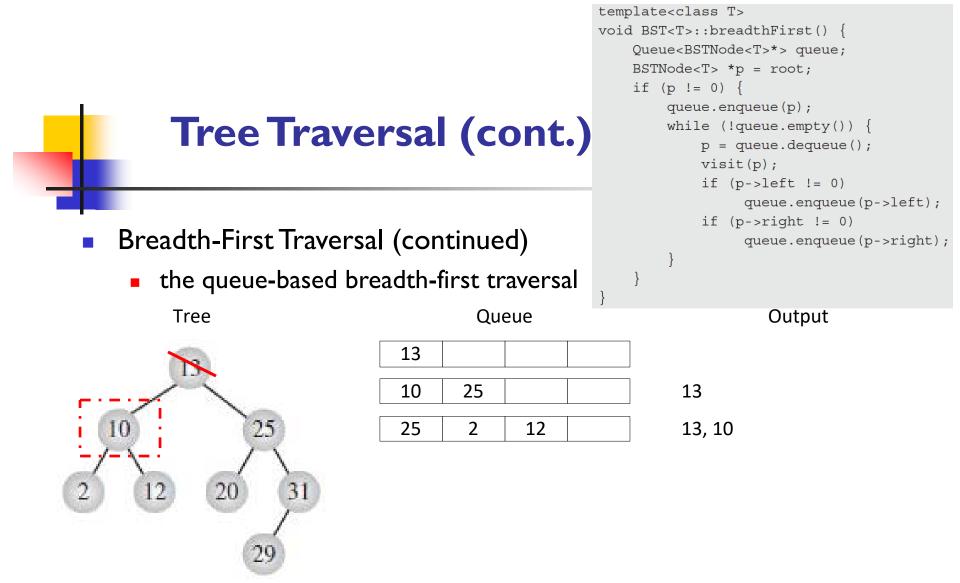




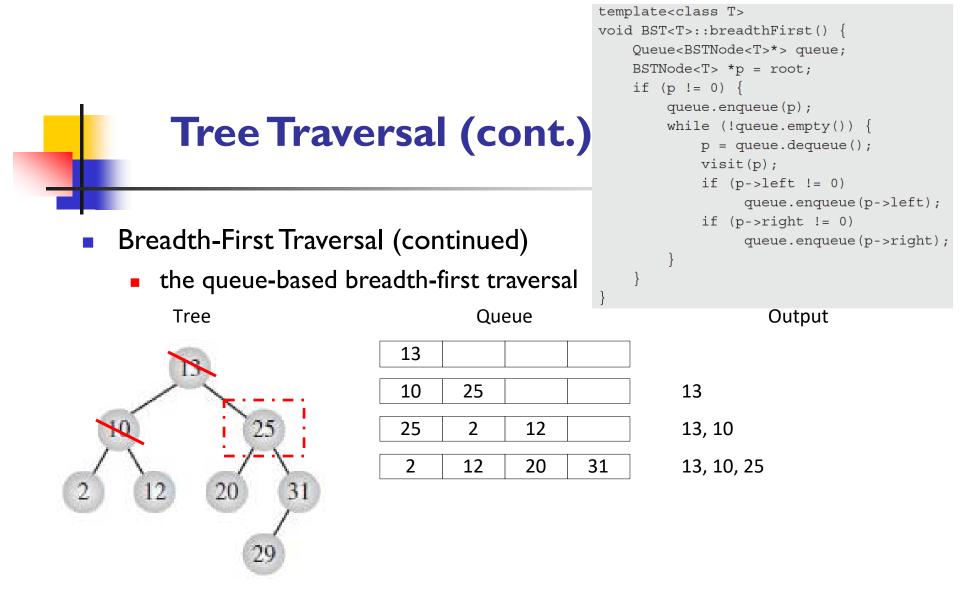




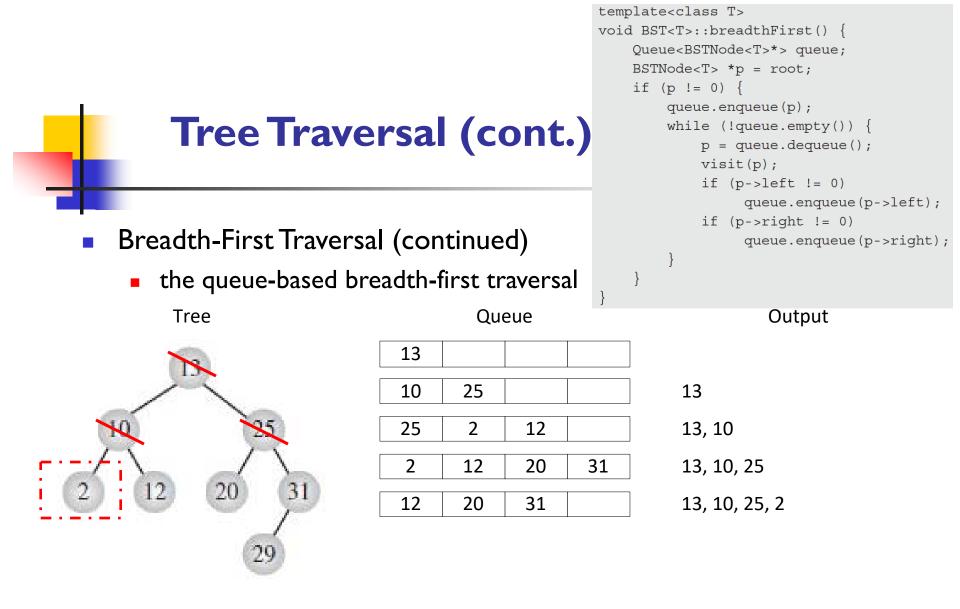




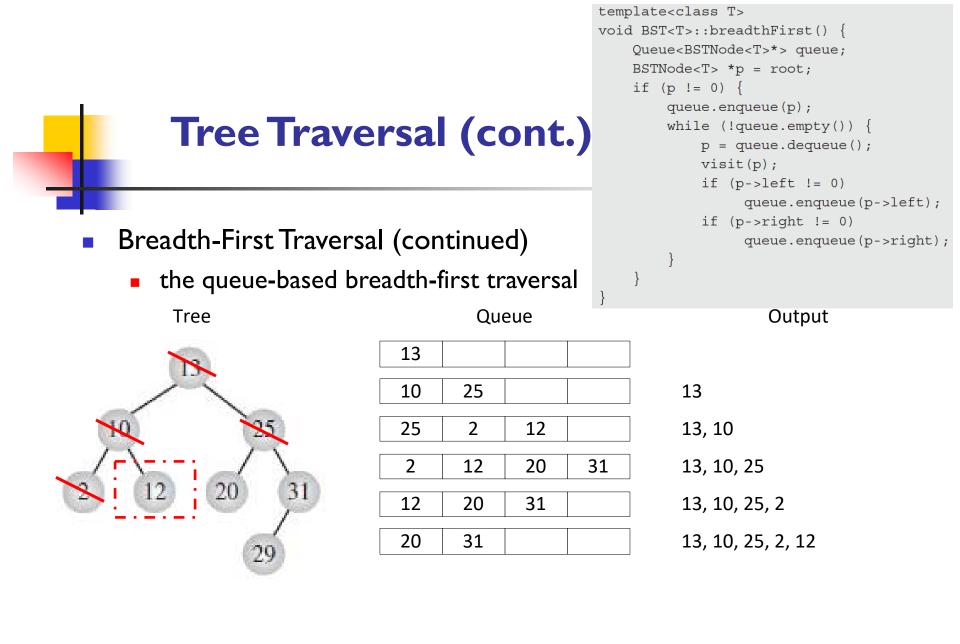




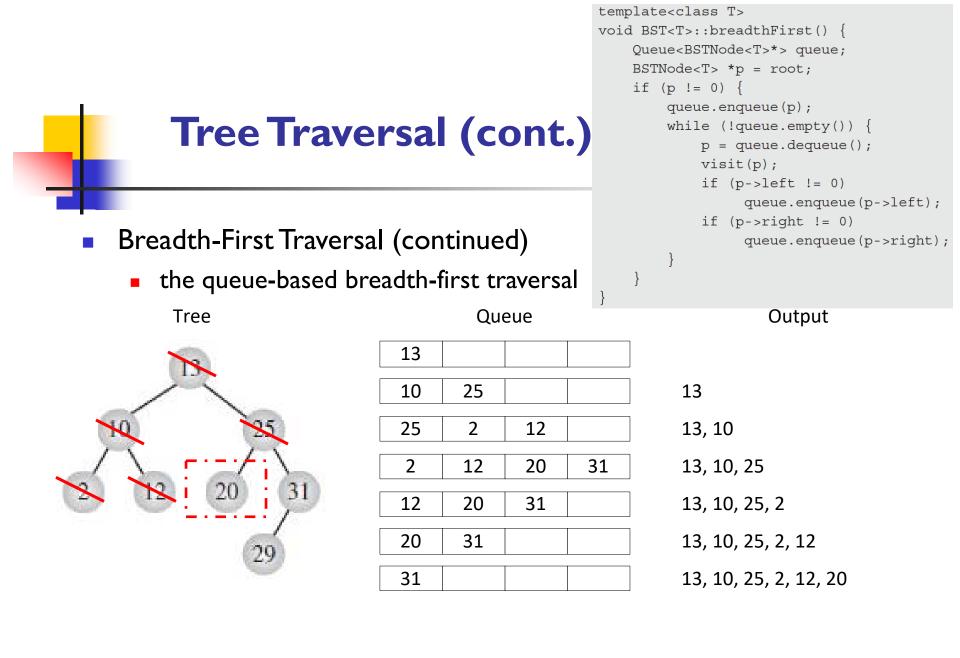




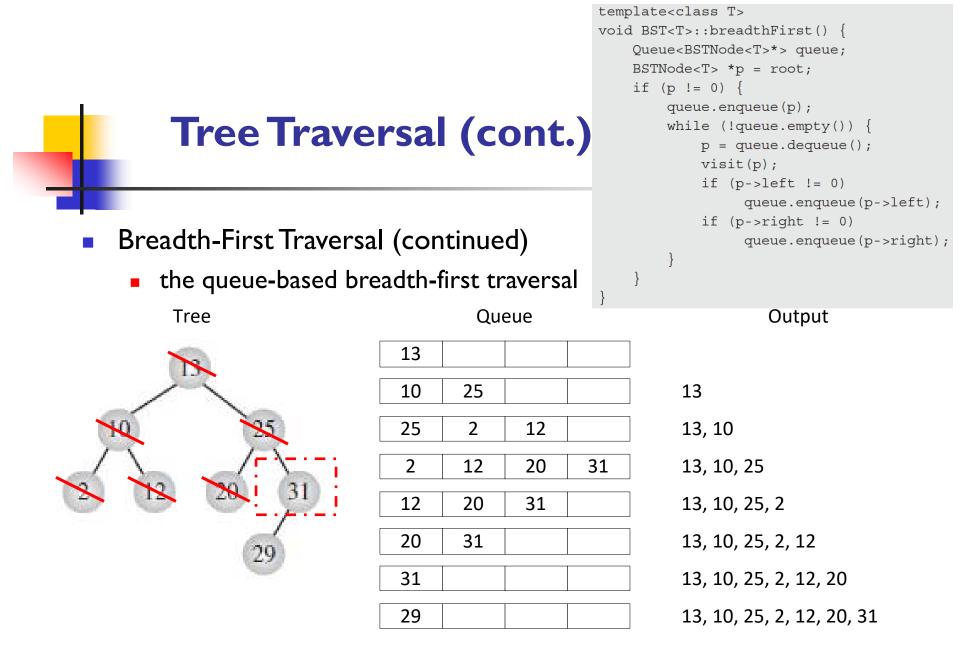




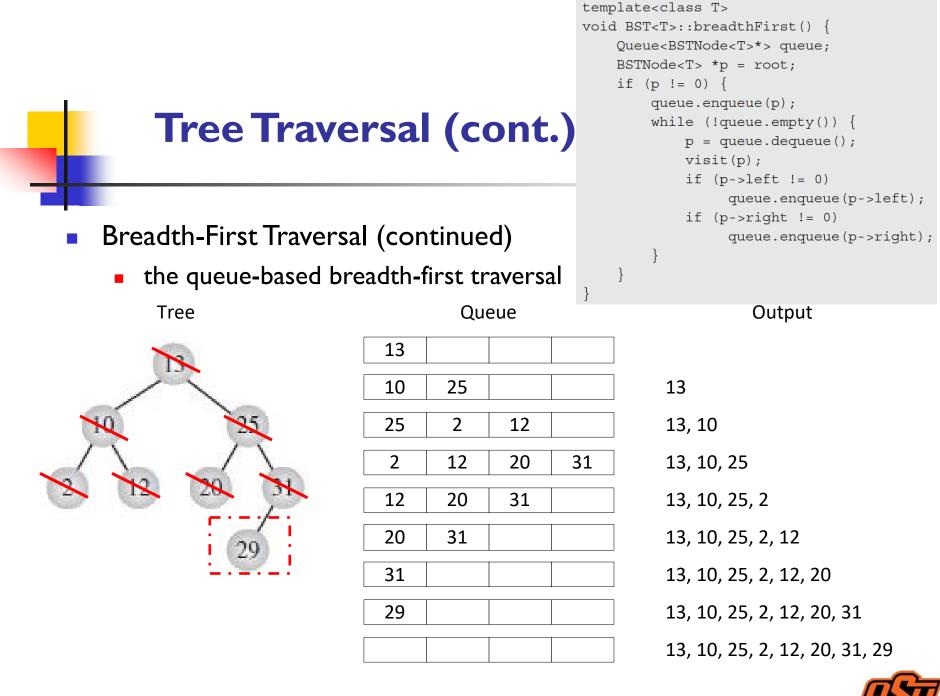


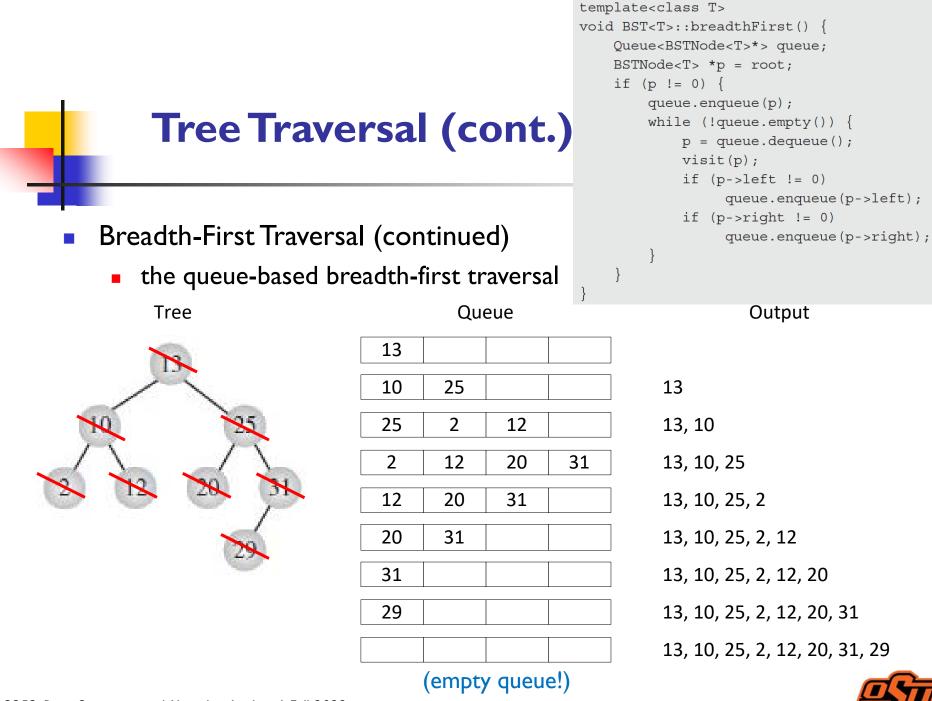












Depth-First Traversal

- proceed by following left- (or right-) hand branches as far as possible
- backtrack to the most recent crossroad and take the right- (or left-) hand branch to the next node
- follow branches to the left (or right) again as far as possible
- continue until all nodes have been visited

(when are nodes visited?? before proceeding down or after backing up??)

- Three activities:
 - traversing to the left subtree (L)
 - traversing to the right subtree (R)
 - visiting a node (V)



- Three activities:
 - traversing to the left subtree (L)
 - traversing to the right subtree (R)
 - visiting a node (V)
- An orderly traversal: the tasks are performed in the same order for each node
- Six possible ordered depth-first traversals

VLR VRL LVR RVL LRV RLV



```
Tree Traversal (c
```

- Depth-First Traversal (continued)
 - follow the convention of traversing from left to right:
 - VLR known as preorder traversal
 - LVR known as inorder traversal

```
template<class T>
void BST<T>::inorder(BSTNode<T> *p)
```

template<class T>

if (p != 0) {

visit(p);

```
if (p != 0) {
    inorder(p->left);
    visit(p);
    inorder(p->right);
```

void BST<T>::preorder(BSTNode<T> *p)

preorder(p->left);

preorder(p->right);

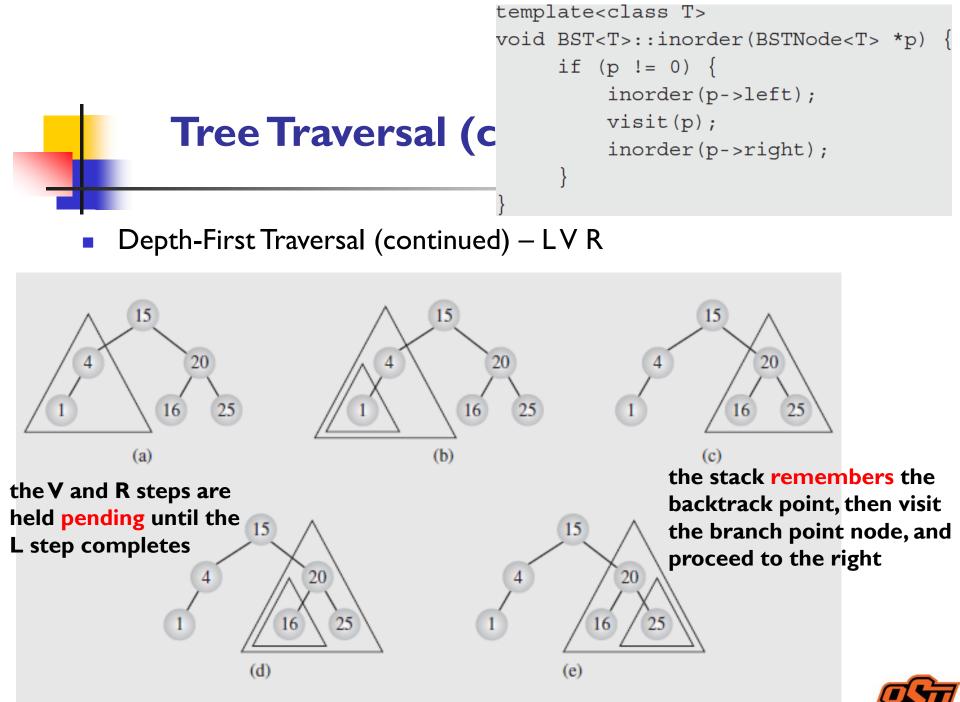
 LRV – known as postorder traversal

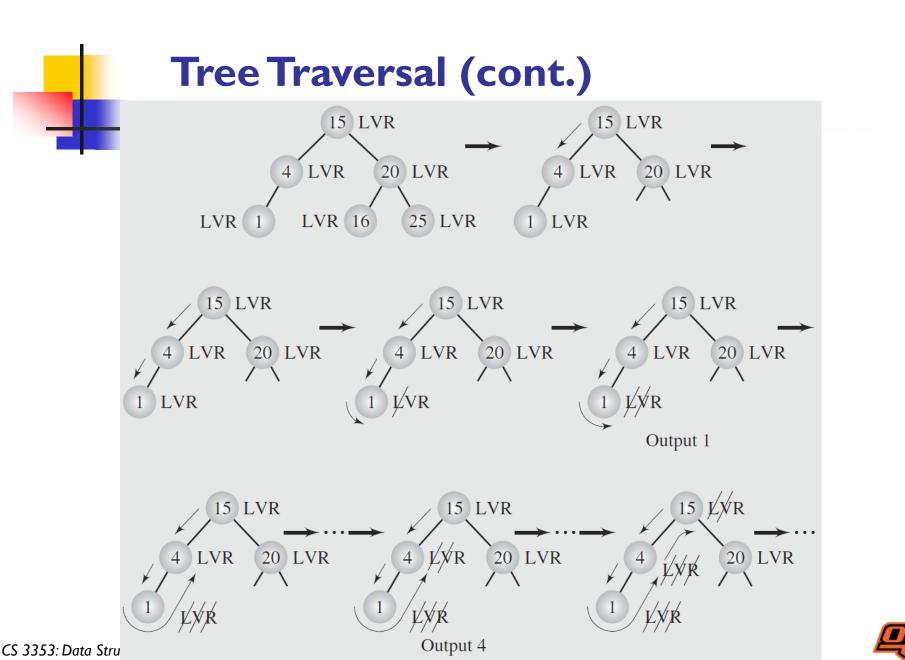
```
template<class T>
void BST<T>::postorder(BSTNode<T>* p)
    if (p != 0) {
        postorder(p->left);
        postorder(p->right);
        visit(p);
    }
}
```

- Depth-First Traversal (continued)
 - the recursion supported by the **run-time stack**
 - simplifying coding but, laying a heavy burden on the system
 - e.g., the **inorder** traversal
 - traverse the left subtree of the node, then visit the node, then traverse the right subtree

```
template<class T>
void BST<T>::inorder(BSTNode<T> *p) {
    if (p != 0) {
        inorder(p->left);
        visit(p);
        inorder(p->right);
    }
}
```







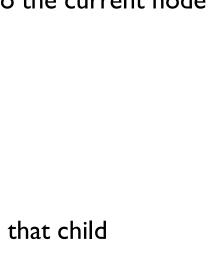
Insertion

- Searching a binary tree
 - does not modify the tree
- Tree traversals can change the tree
 - depending on visit()
 - operations like insertions, deletions, modifying values, etc.
 - alter the tree structure

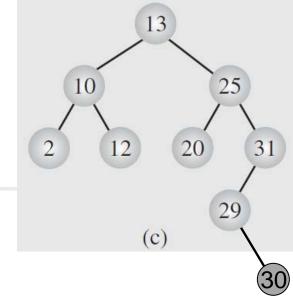


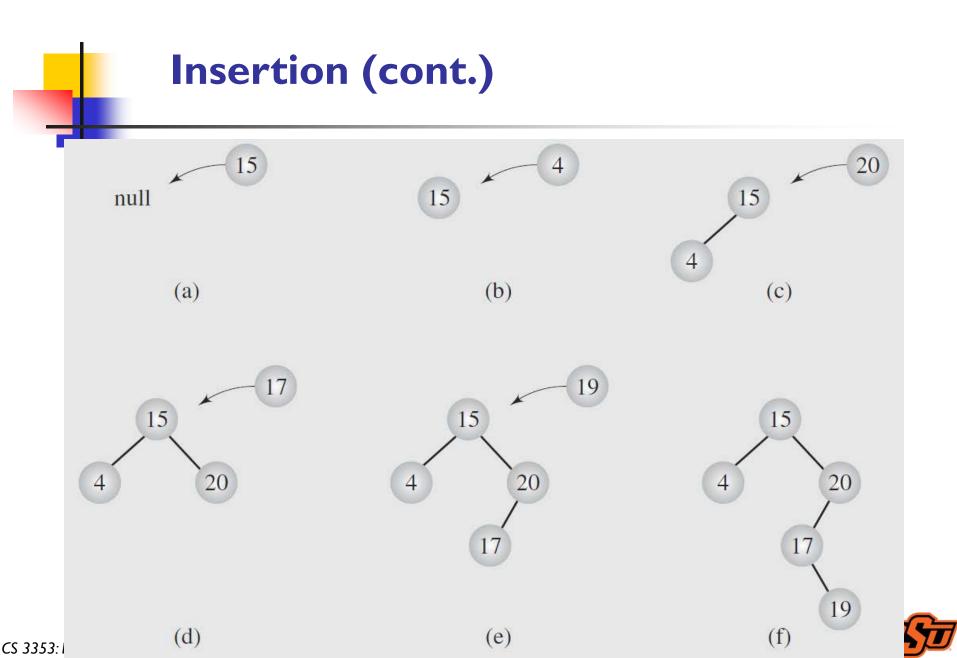
Insertion

- Insert a new node in a binary tree??
 - perform in the same way as searching
 - compare the value of the node to be inserted to the current node
 - if the value to be inserted is smaller,
 - follow the left subtree;
 - if it is larger,
 - follow the right subtree;
 - if the child branch we are to follow is empty,
 - stop the search and insert the new node as that child
 - E.g., insert node 30



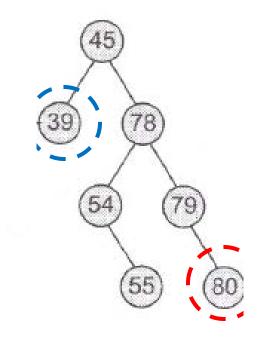








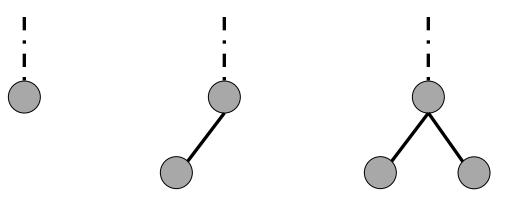
• Finding the smallest or largest node





Deletion

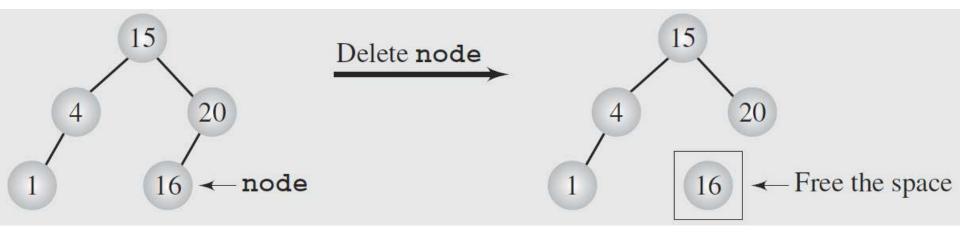
- A complex operation depending on the *placement* of the node to be deleted in the tree
 - more children a node has, more complex the deletion process
- Three cases of deletion that need to be handled:
 - deleting a node that has no children
 - deleting a node with one child
 - deleting a node with two children







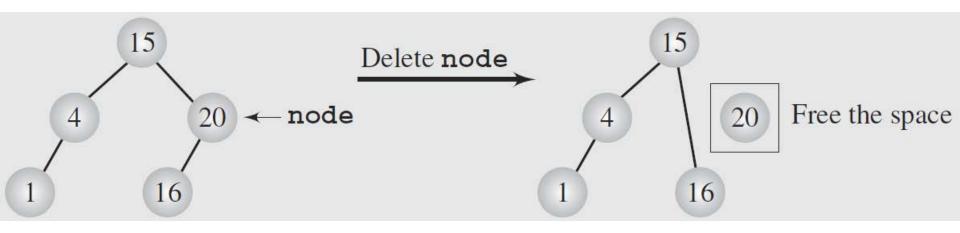
deleting a node that has no children (e.g., delete 78)







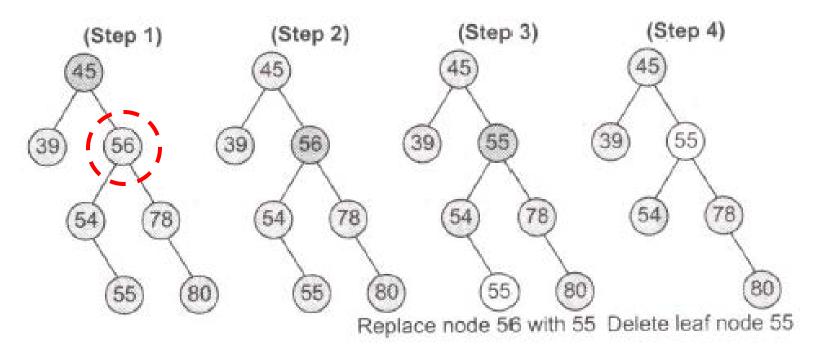
deleting a node with one child (e.g., delete 54)





Deletion

deleting a node with two children (e.g., delete 56)

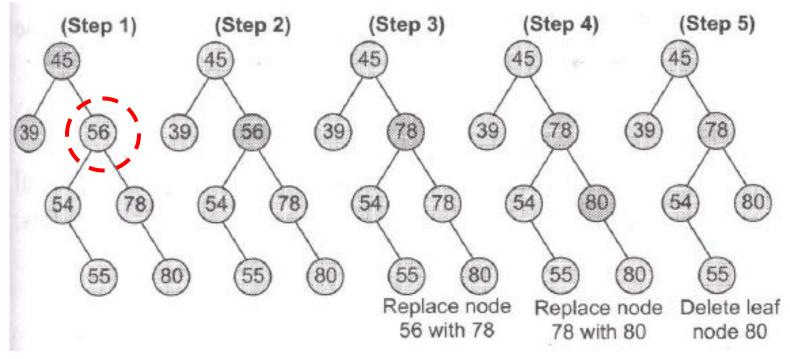


Find the largest value in the left subtree



Deletion

deleting a node with two children (e.g., delete 56) (cont.)



Find the smallest value in the right subtree

