Sorting

Lecture 20

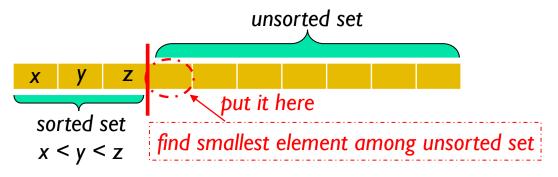
Instructor: Dr. Cong Pu, Ph.D.

cong.pu@okstate.edu

Adapted partially from Data Structures and Algorithms in Java, M.T. Goodrich, R.Tamassia and M. H. Goldwasser, Sixth Edition, Wiley; Data Structures and Algorithms in C++, Adam Drozdek, 4th Edition, Cengage Learning



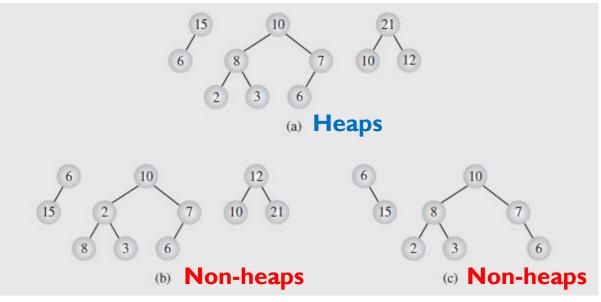
- Motivation of *heap sort*
 - selection sort, fairly inefficient, O(n^2)
 - recall: selection sort finds the smallest element in the list and places it first, then the next smallest, etc.



- relatively *few* moves of the data; *many* comparisons
- if the comparison portion of the sort can be improved?
 - performance can likewise be improved

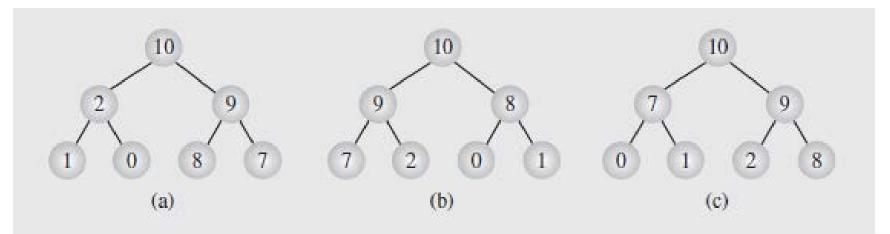


- A heap, a special type of binary tree
 - the value of each node is greater than or equal to the values stored in its children
 - the tree is *perfectly balanced*, and the leaves in the last level are leftmost in the tree





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 - the value of each node is greater than or equal to the values stored in its children
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- Different heaps constructed with the same elements [0 | 2 7 8 9 10]

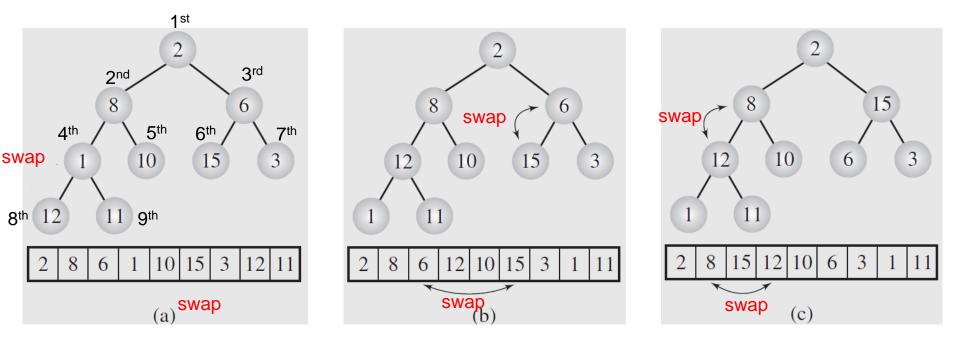




- Heap sort
 - have the array sorted in ascending order
 - place the *first largest element* at the *end* of array;
 - then put the second largest element in front of the first largest element;
 - •••
 - etc.
- Differences between *heap sort* and selection sort
 - heap sort: the largest element; the end of array
 - selection sort: the smallest element; the beginning of array
 - result is same

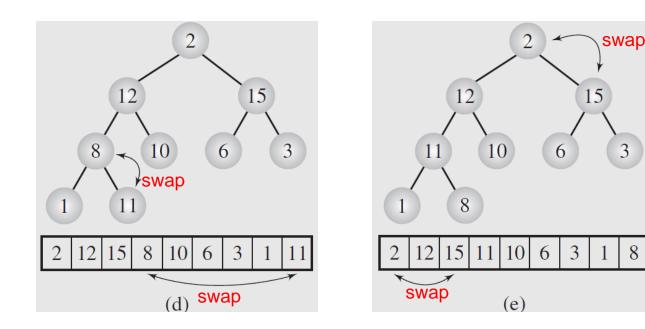


- Two phases of heap sort
 - Ist phase: build a heap out of the data set





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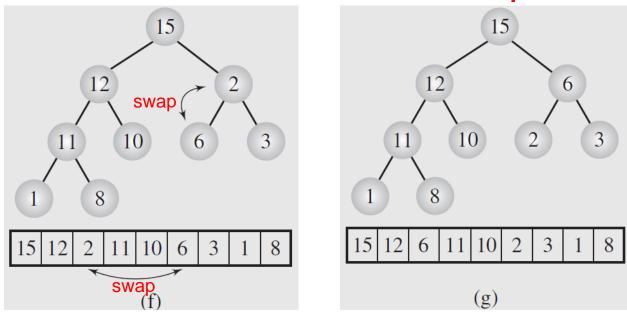




3

8

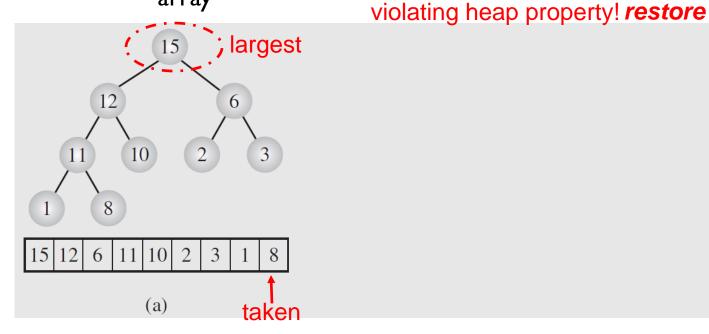
- Two phases of heap sort
 - Ist phase: build a heap out of the data set heap



- the value of each node is greater than or equal to the values stored in its children
- the tree is perfectly balanced, and the leaves in the last level are leftmost in the tree



- Two phases of heap sort
 - Ist phase: build a heap out of the data set
 - 2nd phase: find the largest item from the heap and move it to the end of array

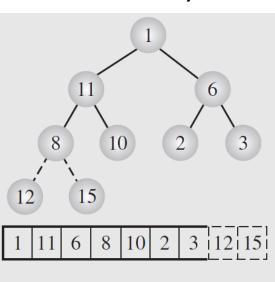


; largest

- Two phases of heap sort
 - Ist phase: build a heap out of the data set
 - 2nd phase: find the largest item from the heap and move it to the end of array violating heap property! restore

taker

; largest

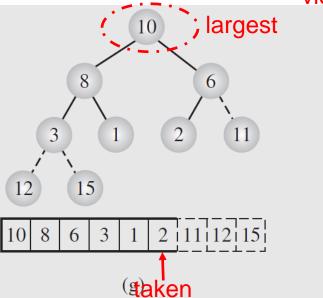


(d) violating heap property! *restore*



- Two phases of heap sort
 - Ist phase: build a heap out of the data set
 - 2nd phase: find the largest item from the heap and move it to the end of

violating heap property! restore



array



Implementation of heapsort()

```
template<class T>
void heapsort(T data[], int n) {
   for (int i = n/2 - 1; i >= 0; --i) // create a heap;
      moveDown (data,i,n-1);
   for (int i = n-1; i >= 1; --i) {
      swap(data[0],data[i]); // move the largest item to data[i];
      moveDown(data,0,i-1); // restore the heap property;
   }
}
```

code for swap () and moveDown () can be found on Canvas



Merge sort

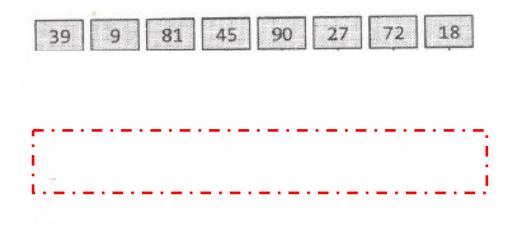
- three major operations:
 - **divide** this process stops when the subarray has one element
 - partition the n-element array to be sorted into two subarray of n/2 elements
 - conquer
 - sort the two sub-arrays recursively
 - combine
 - merge the two sorted sub-arrays of size n/2 to produce the sorted array of n elements



Efficient Sorting Algorithms: Merge Sort (cont.)

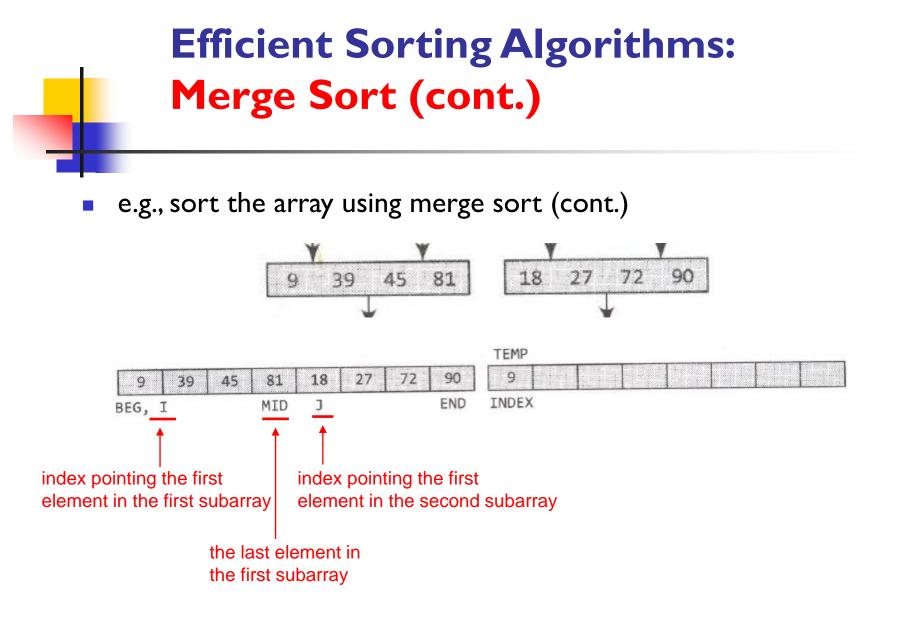
e.g., sort the array using merge sort





(Combine the elements to form a sorted array)







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9		I, MID				J END			here and the second				INDEX				

Efficient Sorting Algorithms: Merge Sort (cont.)

```
mergesort(data[])
   if data have at least two elements
                                               stop when subarray has one item
       mergesort (left half of data);
                                              keep dividing left half
       mergesort (right half of data);
                                               keep dividing right half
       merge (both halves into a sorted list);
merge(array1[], array2[], array3[])
    i1, i2, i3 are properly initialized;
    while both array2 and array3 contain elements
       if array2[i2] < array3[i3]</pre>
              array1[i1++] = array2[i2++];
       else array1[i1++] = array3[i3++];
    load into array1 the remaining elements of either array2 or array3;
```

Key operations

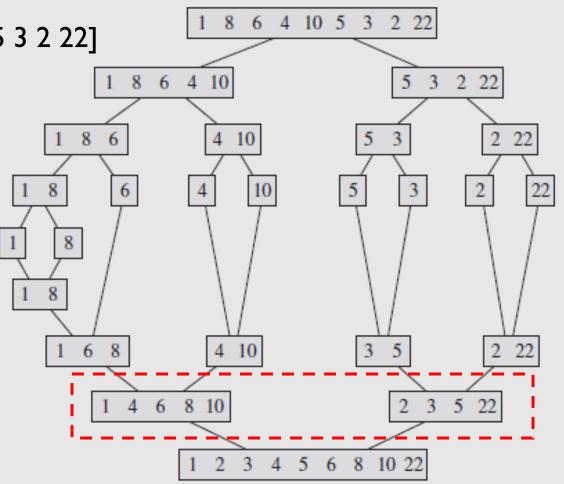
- merge the sorted halves of the array into a single array
- these halves must be sorted, which occurs by merging the sorted halves of these halves



Efficient Sorting Algorithms: Merge Sort (cont.)

- e.g., the array [1 8 6 4 10 5 3 2 22] sorted by merge sort
- Drawback of merge sort?
 - additional storage for

merging array



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