

# Defending against Flooding Attacks in the Internet of Drones Environment

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# Outline

- Introduction & Motivation
- Related Work
- Proposed Flooding Attack Detection
  - System Model
  - Lightweight Distributed Detection Scheme
- Performance Evaluation
- Conclusion

# Introduction

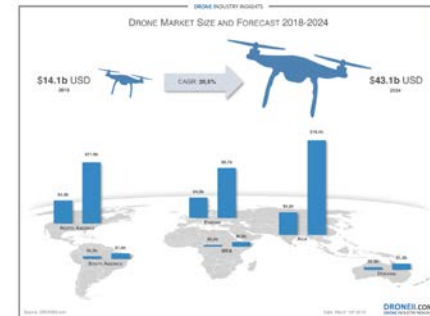
- The potential of drones is being constantly exploited...

- a military weapon
- an entertainment tool
- a machinery that can revolutionize mobile networks



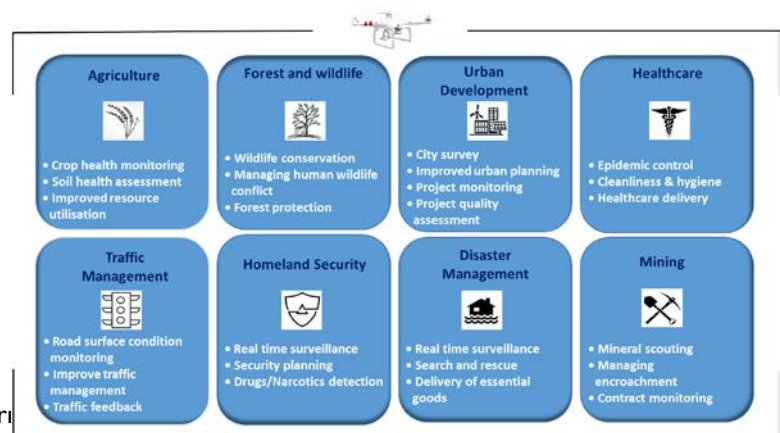
- “Global Drone Market Report 2020-2025”

- the international drone market is estimated to be around **\$44 billion** by 2024



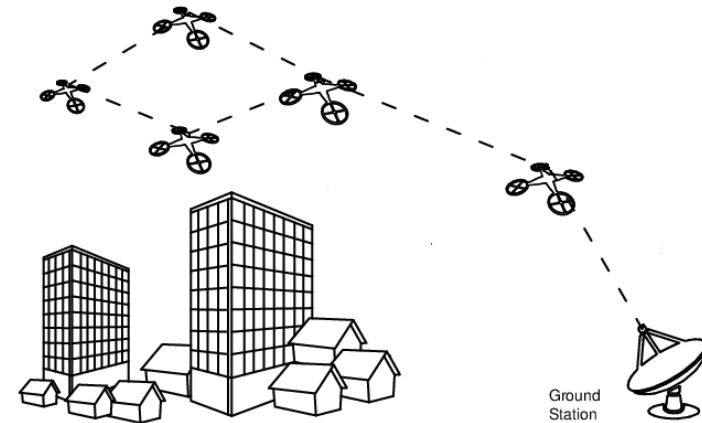
- The demand for drones by various unites is high

- drones can be flexibly deployed for a wide range of applications



# Introduction

- To fully exploit drones, **Internet of Drones (IoD)** is proposed
  - mobile drones
  - stationary ground stations
    - acts as access point
  - drone-to-drone (D2D) comm.
  - drone-to-ground station (D2I) comm.



- The IoD is lack of persistent connectivity
  - between drone and drone, and between drone and ground station

## — store-carry-and-forward strategy —

*the most promising candidate for delivering data in the IoD*

a drone stores the received packets in the storage, carries them while flying around, and forwards them to the next-hop drone or destination (i.e., ground station)

# Motivation

- As a result of high mobility and resource constraints, the IoD is vulnerable to *flooding attacks*
  - an adversary sends an excessive amount of packets (original or replica) to legitimate drones
    - draining the limited IoD resources such as communication bandwidth and drones' storage space
- *Flooding attacks* has serious consequences
  1. the link expiration time (for D2D and D2I) is **short**
    - a mass of attack packets waste precious commu. time
  2. the storage capacity of drones is **limited**
    - buffering attack packets prevent from storing genuine packets
  3. the battery energy of drones is **constrained**
    - receiving and sending attack packets consume energy power

# Motivation (cont.)

- *Flooding attacks* are an old research topic in diverse environments
    - traditional computer network
    - named data networking
    - wireless ad hoc network
    - vehicular ad hoc network
    - etc.
  - no/low mobility is considered
  - existing schemes do not apply in IoD
- 
- In addition, there is no available work concentrating on flooding attacks and their countermeasures in the IoD
    - our work fill this research gap

# Our Contribution

- This paper
  - proposes a lightweight distributed detection scheme (Lids) to defend against flooding attacks in the IoD environment
    1. each drone counts the number of packets that it has sent within a predefined time interval and shares the self-counting report with other drones during contacts
    2. the receiving drones store the self-counting reports while flying and send them to nearby ground station which will check the consistency of self-counting reports to detect flooding attacks

# Most Countermeasures in the IoD

- multi-path packet forwarding scheme against jamming attack [14]
  - select multiple paths between src. and des. based on network metrics
  - frequent metrics calculation results in computational overhead
- clustering based scheme against packet dropping attack [15]
  - the behaviors of drones are evaluated and converted into trust
  - non-negligible energy consumption from clustering maintenance
- blockchain based data management framework [17]
  - access control mechanism and secure session key
  - a consensus algorithm for the competition of adding block
  - has several serious vulnerabilities [18]



# Most Countermeasures in the IoD

- RREQ flooding attack in wireless ad hoc network [20]
  - Bayesian Inference models and detects RREQ flooding attack
  - **no mobility is considered**
- intrusion detection system [21]
  - deep neural network technique to combat data flooding attack
  - **energy consumption due to running deep neural network tech.**
- flooding attack defense scheme in vehicular network [22]
  - the packet traffic of each vehicle is monitored
  - the statistics and traffic flow rules detect flooding attack
  - **dense placement of road-side unites (RSU)**
    - **deployment and operational costs increase**

# Most Countermeasures in the IoD

- Two important issues should be addressed to detect flooding attacks in the IoD
  - i. intermittent connectivity in the IoD
    - taking advantage of store-carry-and-forward strategy
  - ii. integration with off-the-shelf routing protocols
    - designing countermeasure as a network layer add-on module
  
- This paper provides
  - in-depth analysis of flooding attacks
  - countermeasure against flooding attack
    - **Lids**: Lightweight Distributed Detection Scheme
  - bridge the research gap

# Lids: System Model

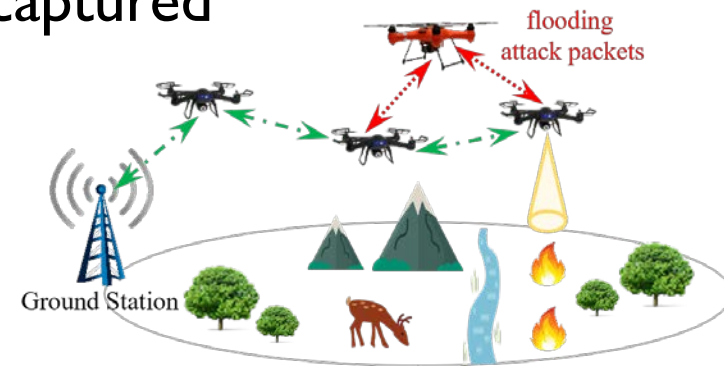
- A genetic IoD scenario (i.e., search and rescue)
  - a set of drones is deployed in the area
  - when a drone detects an event
    - generates data packets
    - sends them to nearby ground station
      - multi-hop relays
  - end-to-end forwarding path does not always exist
    - store-carry-and-forward strategy
      - stores received packets
      - carries them while flying
      - forwards them to next-hop (i.e., drone or ground station)
  - drone has limited storage space
    - a timer is used to purge stale packets
  - public-key cryptography [23] is being utilized



# Lids:

## Adversary Model

- In wide-open airspace, drones can be captured
  - compromising legitimate drones
  - making them behave maliciously
- The primary goal of adversary
  - flooding a large number of original or replica packets
  - draining the limited IoD resources
    - communication bandwidth
    - drones' storage space and energy resource



# Lids:

## Lightweight Distributed Detection Scheme

- When the drone (i.e.,  $ID_a$ ) joins the IoD, it registers at the certificate authority (CA)
  - negotiate an agreement on the **packet send rate**,  $RT_a^{pkt}$ .
    - $RT_a^{pkt}$ : indicates the number of packets that the drone can send within a pre-defined time period,  $T^\omega$ .
      - if the drone sends more packets than  $RT_a^{pkt}$ , it is suspected as adversary.
  - the CA issues a digital certificate,  $CERT_a$ , to the drone  $ID_a$ 
    - $CERT_a$  includes
      - drone's identity  $ID_a$
      - drone's public key  $PU_a$
      - drone's packet send rate  $RT_a^{pkt}$
      - CA's digital signature
  - the CA also generates a private key,  $PR_a$ , and issues it to drone  $ID_a$  via a secure channel.

# Lids:

## Lightweight Distributed Detection Scheme

- When the drone (i.e.,  $ID_a$ ) contacts with another drone (i.e.,  $ID_b$ )
  - the drone  $ID_a$  first sends scheduled packets to drone  $ID_b$
  - the drone  $ID_a$  then sums up the number of sent packets,  $CNT^{pkt}$ , since the beginning of current time interval,  $T_i^\omega$ .
  - the drone  $ID_a$  creates the self-counting report,  $RPT_a^{T_x}$ , and shares it with drone  $ID_b$ 
    - $RPT_a^{T_x}$  contains
      - the count of sent packets  $CNT^{pkt}$
      - the contact time  $T_x$
      - drone  $ID_a$ 's digital certificate  $CERT_a$
      - drone  $ID_a$ 's digital signature  $SIG_a$
      - message authentication code  $MAC_{T_x}$
    - $RPT_a^{T_x} = \{CNT^{pkt}, T_x, CERT_a, SIG_a, MAC_{T_x}\}$ 
      - $SIG_a = E(ID_a|CERT_a|PR_a)$
      - $MAC_{T_x} = H(CNT^{pkt}|T_x|CERT_a|SIG_a)$

# Lids:

## Lightweight Distributed Detection Scheme

- After receiving the report  $RPT_a^{Tx}$ , drone  $ID_b$  verifies  $MAC_{Tx}$ .
  - if  $MAC_{Tx}$  is valid, drone  $ID_b$  verifies  $SIG_a$ 
    - if  $SIG_a$  is valid, drone  $ID_b$  retrieves the packet send rate  $RT_a^{pkt}$  and the digital certificate  $CERT_a$ , and compares it with the count of sent packets  $CNT^{pkt}$ 
      - if  $CNT^{pkt} > RT_a^{pkt}$ 
        - drone  $ID_a$  sends more packets than permitted
        - drone  $ID_b$  discards all received packets
          - save  $RPT_a^{Tx}$  for ground station to detect flooding attack
      - if  $CNT^{pkt} \leq RT_a^{pkt}$ 
        - drone  $ID_b$  carries received packets and delivers them to next-hop drone or ground station

# Lids:

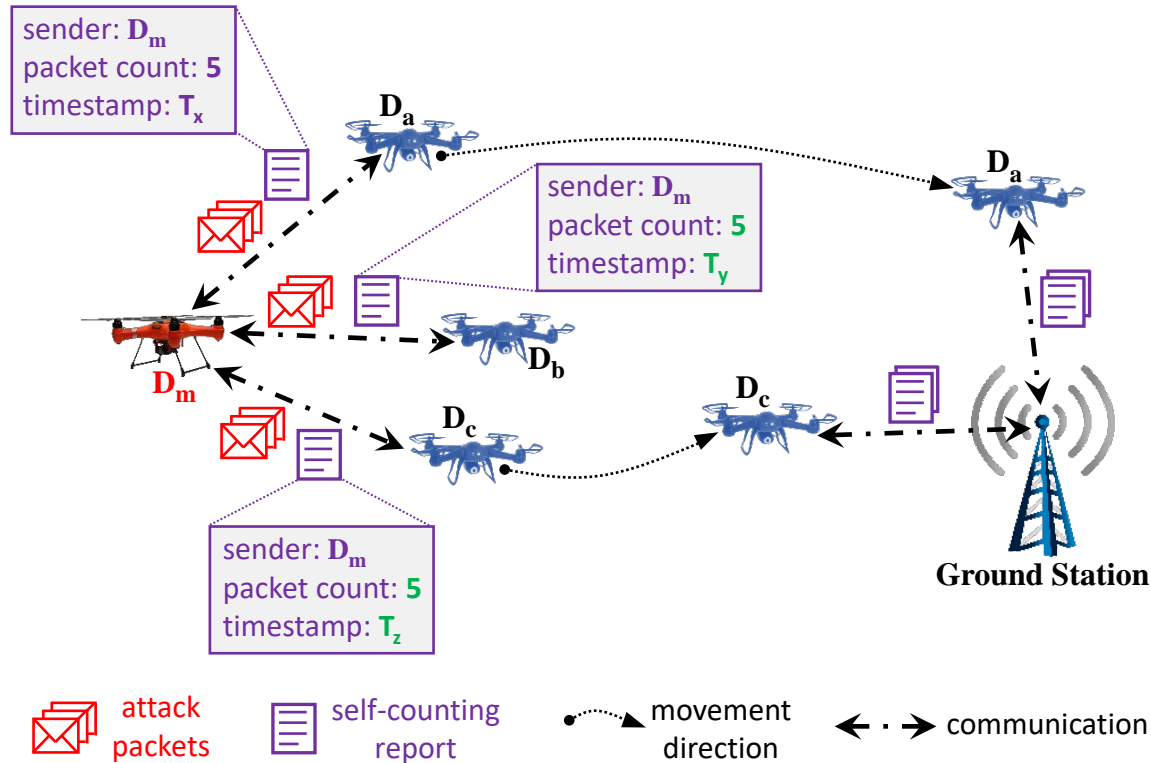
## Lightweight Distributed Detection Scheme

- When drone  $ID_b$  reaches the ground station, it submits all received self-counting reports
- The ground station will compare the newly received reports with the already obtained reports
  - identify whether a drone issues multiple reports with inconsistent information
    - an adversary may disloyally report a false packet count to avoid detection
    - however, this misbehavior can be easily detected
      - the false packet count must have been reported before by adversary;
      - or the false packet count is smaller than or equal to a packet count which was reported in an earlier self-counting report
  - detect flooding attack



# Lids:

## Lightweight Distributed Detection Scheme



# Performance Evaluation

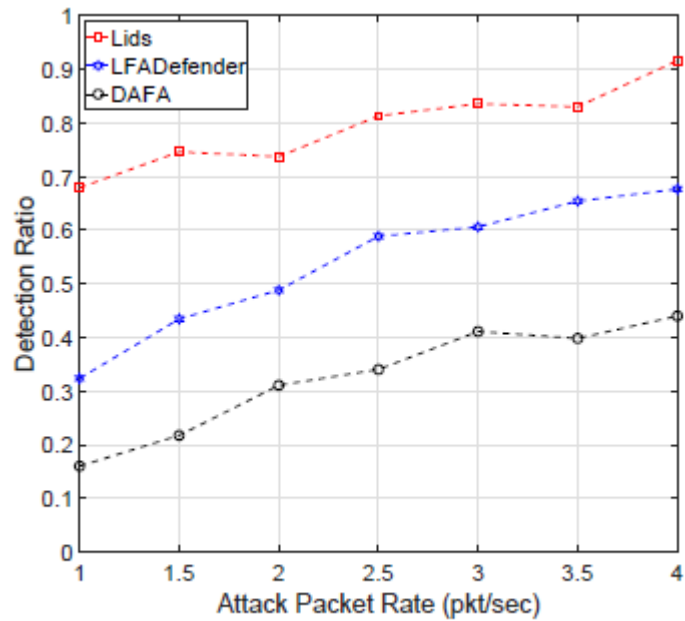
- Performance metrics
  - Detection Ratio
  - Miss Detection Ratio
  - Detection Latency
  - Energy Consumption
- Benchmark schemes
  - DAFA [12]
    - packet transmission rate
  - LFADefender [13]
    - packet loss rate, round-trip time, and available bandwidth

TABLE I  
SIMULATION PARAMETERS

Parameter	Value
Network area	150×150 $m^2$
Number of legitimate drones	35
Number of malicious drones	5
Number of ground stations	3
Moving speed	15 meter/sec
Mobility model	Random waypoint
Communication range of drone	12.59 meters
Communication range of ground station	50 meters
Radio data rate	3 Mbit/sec
Packet size	127 bytes
Attack packet rate	1.0 - 4.0 pkt/sec
Simulation time	10,000 seconds

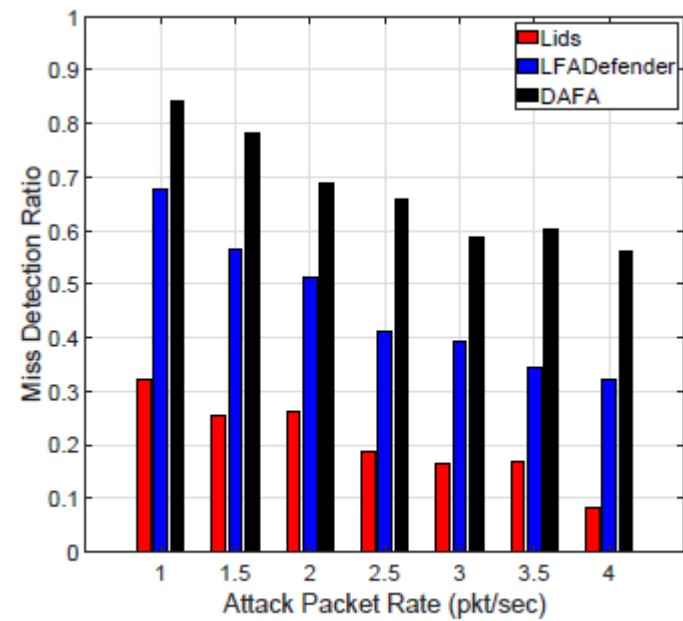
# Performance Evaluation (cont.)

## Detection Ratio



(a)

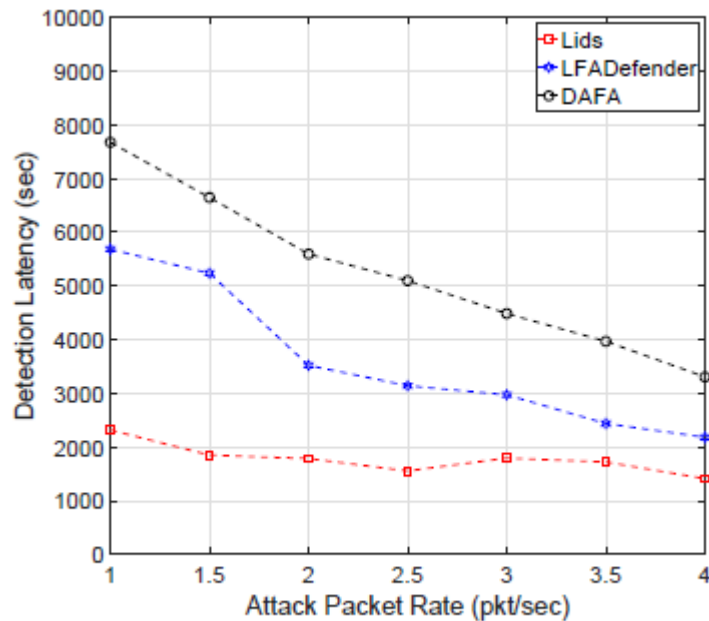
## Miss Detection Ratio



(b)

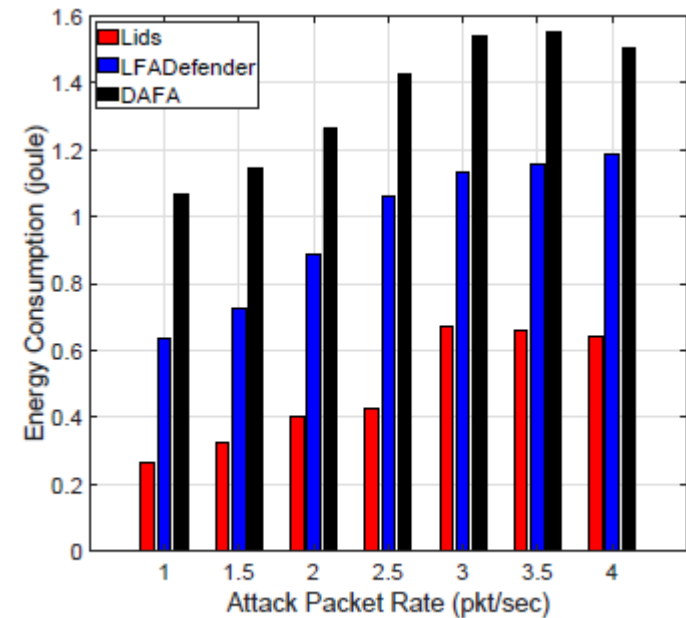
# Performance Evaluation (cont.)

## Detection Latency



(a)

## Energy Consumption



(b)

# Concluding Remarks

- Develop a lightweight distributed detection scheme to defend against flooding attacks in the IoD environment
  - each drone counts the number of sent packets and shares the self-counting report with other drones
  - the receiving drones store the self-counting reports and send them to the nearby ground station
  - the ground station evaluates all self-count reports to detect flooding attack
  
- Under investigation...
  - a large number of self-counting reports to be exchanged
  - data reduction strategy
  - a real-world testbed to explore the full potential of *Lids*

*Any Questions?*